Alexandrov Existence and Uniqueness Theorem for compact surfaces

François Fillastre Université de Cergy–Pontoise France

Alexandrov Theorem for compact surfaces

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A.D. Alexandrov, 1942

Let m(0, +) be a flat (0-curvature) metric on the sphere S^2 with conical singularities of positive singular curvature. Then

- Solution There exists a convex polytope P in ℝ³ such that P realizes m(0, +) (i.e. the induced metric on P is isometric to m(0, +)).
- *P* is unique, up to congruences.

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The proof extends easily to the other constant curvatures

A (1,+)-metric on the sphere is realized by a unique (up to congruence) convex polytope in the 3-d sphere.

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- A (1,+)-metric on the sphere is realized by a unique (up to congruence) convex polytope in the 3-d sphere.
- A (-1,+)-metric the sphere is realized by a unique (up to congruence) convex polytope in the 3-d hyperbolic space.

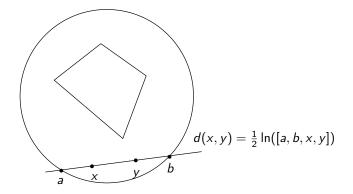
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Original statement for the sphere

A convex polytope is a projective object. Model spaces are (pseudo)-spheres in a vector space.

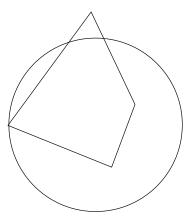
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Of course, induced metric is not a projective data. But one way to prove such results is to prove first an infinitesimal rigidity result.

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But one way to prove such results is to prove first an infinitesimal rigidity result.

And infinitesimal rigidity is a projective property!

Interlude on projective nature of infinitesimal rigidity

Darboux, Sauer, Knebelman 1930, Pogorelov, Volkov

Let (M, g) and (M, \overline{g}) be two (pseudo-)Riemannian manifolds and f a map sending geodesics of g to geodesics of \overline{g} . Let $\lambda = |\overline{g}|/|g|$. Let K be a Killing field of (M, g). Then the vector field \overline{K} of (M, \overline{g}) defined by

$$\overline{g}(\overline{K},X) = g(\lambda^{\frac{1}{n+1}}K,X), \quad \forall X \in TM,$$

is a Killing field of (M, \overline{g}) .

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Interlude on projective nature of infinitesimal rigidity

The proof is a simple consequence of the Weyl equation for connections having the same geodesics

$$\overline{\nabla}_X Y - \nabla_X Y = \frac{1}{2} \frac{1}{n+1} (X \cdot \ln \lambda) Y + \frac{1}{2} \frac{1}{n+1} (Y \cdot \ln \lambda) X.$$

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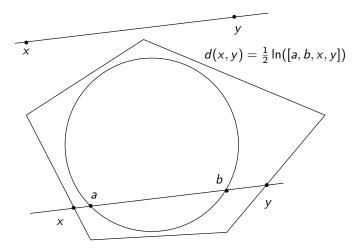
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There is another interpretation based on infinitesimal rigidity of frameworks (see Ivan Izmestiev).

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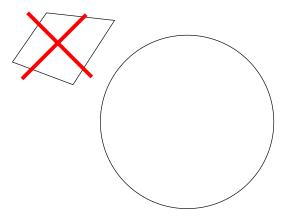
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So we can realize *Riemannian* metrics on the sphere in de Sitter space.

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Rivin-Hodgson, Inventiones, 1993

Let m(1, -) be a spherical metric on the sphere with conical singularities of negative singular curvature [and length of contractible geodesics $> 2\pi$]. Then

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By projective duality, this theorem is equivalent to a realization theorem for hyperbolic polyhedra with prescribed Gauss image.

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• Due to Gauss-Bonnet formula, there does not exist other (K, ϵ) -metric on the sphere, $K \in \{-1, 0, 1\}, \epsilon \in \{-, +\}$, than (0, +), (1, +), (-1, +), (1, -).

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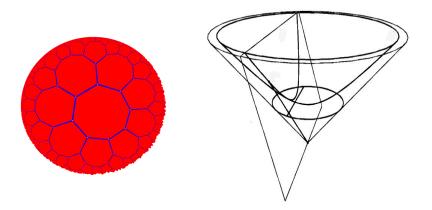
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- So the question is: what about (K, ε)-metrics on compact surface of higher genus?
- We can't realize them as convex polyhedra, as compactness+convexity ⇒ genus 0.
- We will realize the universal cover of the metric, as a convex polyhedral surface equivariant under the action of the fundamental group.

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Take the convex hull of the vertices of the tiling *in the ambiant Minkowski space*.

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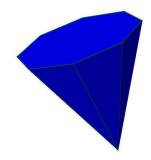
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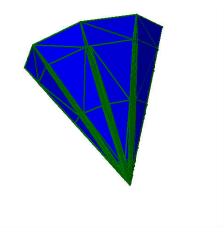
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The quotient of this polyhedral surface is a compact surface of genus 2 with a flat metric with one conical singularity of curvature $2\pi - 8 \times \frac{3\pi}{4} = -4\pi < 0$ (cone-angle 6π).



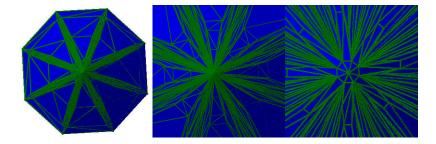
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Alexandrov Theorem for compact surfaces

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Alexandrov Theorem for compact surfaces

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In the projective model of hyperbolic 3d space, horospheres are ellipsoids tangent to the unit sphere and isometric to the Euclidean space.

Example of hyperbolic torus

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 $\mathbb{Z} \times \mathbb{Z}$ acts by isometries on a horosphere. The convex hull of the orbit of one point is a simpliest example of a convex *parabolic* polyhedra.

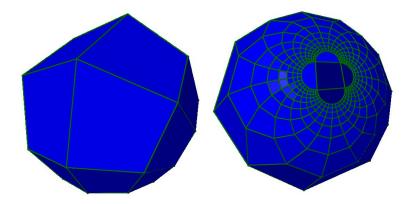
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The quotient is a torus with a hyperblic metric with one conical singularity of positive curvature.

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Example of hyperbolic torus



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• The curvature $K \in \{-1, 0, 1\}$.

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- The curvature $K \in \{-1, 0, 1\}$.
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By Gauss–Bonnet, there are only 10 possible (K, ϵ, g) .

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$g K \epsilon$

Alexandrov Theorem for compact surfaces

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$$\begin{array}{cccc} g & K & \epsilon \\ \hline 0 & -1 & + \\ \end{array} A.D. Alexandrov$$

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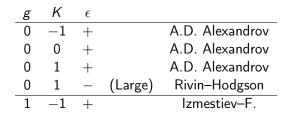
g	K	ϵ	
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Alexandrov Theorem for compact surfaces

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The general statement

S is a compact surface of genus g. $K \in \{-1, 0, 1\}$, $\epsilon \in \{-, +\}$.

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Let *m* be a (K, ϵ) -metric on *S* (large for (1, -)). Then

- There exists a convex polyhedral surface P ⊂ M^ε_K and a group of isometries Γ, acting cocompatly on a totally umbilic surface, such that P/Γ is isometric to (S, m).
- **2** (P, Γ) is the unique couple of this kind, up to congruences.

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Благодарю вас за внимание

Alexandrov Theorem for compact surfaces